

**IN THE ABSTRACT:**

The Abstract as amended below with a replacement Abstract shows added text with underlining and deleted text with ~~striketrough~~.

Please DELETE the Abstract in its entirety and substitute the attached new Abstract.

~~AA~~A work tool mounted on an arm tip end of a robot is allowed to move toward a teaching point of a robot operation program, and to stop the work tool before it reaches the teaching point. The robot is moved by jog feeding from the stopped position to a target position. In this manner, the teaching point of the robot operation program is corrected.